AMENDMENT UNDER 37 C.F.R. § 1.111 Attorney Docket No.: Q86512

Application No.: 10/525,653

AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions and listings of claims in the application:

LISTING OF CLA	IMS:	
Claim 1 (cur	rently amended):	An implantable mechanical device with adjustable
geometry, comprising	ng:	
	—an input part (1) hav	ing a first cylindrical end (11),
	—an output part (2), h e	aving two second (21) and third (22) cylindrical ends,
which are opposite one another, and which are aligned, and where the second cylindrical end		
(21) has a diameter	equal to that of the said	l first cylindrical end (11) ,
	—a reference part (3)4	naving a fourth cylindrical end (31) of the same
diameter as the said	third cylindrical end (2	22) ,
	-a transported part (4), having a helicoidal link (51, 52) with the said outpu
part (2),		
	means to apply an al	Iternative rotational movement to said input part (1),
mean	ns to block rotation of t	he said reference part (3) relatively to a part of the
organism and		
mean	ns to bind the said trans	ported part (4) to a part of the organism,
wherein:		
	the said input part ha	ave a first cylindrical end (11)

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Application No.: 10/525,653 the said output part have two second (21) and third (22) cylindrical ends, which are opposite one another and which are aligned, and where the second cylindrical end (21) has a diameter as the said third cylindrical end (22) and the device further comprises: means to hold the axes of the said first (11), second (21) and fourth (31) cylindrical ends in alignment with the axes of the said helicoidal link (51, 52), and to hold juxtaposed, firstly, the said first cylindrical end (11) and the said second cylindrical end (21) and, additionally, the said third cylindrical end (22) and the said fourth cylindrical end (31), whilst allowing rotation of the said input part (1) and of the said output part (2), relative to the said reference part (3), around the said axis of the said helicoidal link (51, 52), at least one first friction spring (7) having an unloaded internal diameter slightly less than the common diameter of the said first (11) and second (21) cylindrical ends on which it is mounted by force, so as to straddle them, at least one second friction spring (8) wound in the opposite direction to the winding of the said first friction spring (7), and having an unloaded internal diameter slightly less than the common diameter of the said third (22) and fourth (31) cylindrical ends on which it is mounted by force, so as to straddle themmeans to bind the said transported part (4) to a part of the organism, means to apply an alternative rotational movement to the said input part (1) from outside the organism.

organism.

means to block rotation of the said reference part (3) relatively to a part of the

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Claim 2 (currently amended): A device according to claim 1, wherein the means to apply an alternative rotational movement to the said input part (1) an alternative rotational movement from outside the organism comprise means to link to at least one bone segment.

Claim 3 (currently amended): A device according to claim 1, wherein the means to apply an alternative rotational movement to the said input part (1) from outside the organism comprise means placed in the soft tissues.

Claim 4 (currently amended): A device according to claim 1, wherein the means to apply an alternative rotational movement to the said input part 1 from outside the organism comprise elastic means.

Claim 5 (currently amended): A device according to claim 2, wherein the means to apply an alternative rotational movement to the said input part 1 from outside the organism comprise elastic means.

Claim 6 (currently amended): A device according to claim 3, wherein the means to apply an alternative rotational movement to the said input part 1-(1) from outside the organism comprise elastic means.

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